

MVP-R

Proportional Valve Ramping Controller



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Welcome

Welcome to **High Country Tek** Inc. HCT is North America's foremost independent designer and producer of modular, ruggedized digital and analog electronic controllers for the fluid power industry.

From our factory in California, we manufacture 'specialty' controllers for specific functions and the user programmable 'DVC family' to enable large area networked system solutions.

The modules are used in mobile, industrial and marine applications. They are also applied successfully in other industry segments.

HCT products are encapsulated in solid flame resistant material for maximum durability, electrical integrity and complete environmental security.

HCT is a market leader in many application arenas, including hydraulic generator, e-Fan and hydraulic fan system controls. These controllers facilitate significant fuel, emission and operational savings.

HCT's market neutrality offers integration with any hydraulic OEM valves, pumps, sub-systems or systems.

For more information, please visit us at: www.hctcontrols.com.

Cautions

Changing setup values or operating modes while a machine is running may cause unintended machine movement. It could lead to possible **injury** or **death**. Any moving parts should be disabled prior to changing setup values or operating modes. In every case, exercise caution and work should be completed only by qualified personnel.

Product Application Guidelines

ALWAYS do the following

- FULLY read this manual and accompanying data sheets BEFORE starting.
- Isolate this unit from all other equipment BEFORE any form of welding.
- Isolate the controller from ANY form of battery charging or battery boosting.
- Be aware of the electrical & mechanical connections, and the expected reactions of the equipment.
- Operate the units within the temperature range.
- Use the correct tools to do the job (i.e. P.C., software) etc.
- Separate High Voltage AC cables from Low Voltage DC signal and supply cables.
- Make sure power supply is CORRECT, ELECTRICALLY CLEAN, STABLE, and rated for the full load.
- Make sure the controller output voltage & current is compatible with the equipment.
- All unused wires / terminals should be terminated safely.
- Ensure ALL connectors have no unintended SHORT or OPEN circuits.
- Ensure ALL connectors are wired correctly, secure, locked in place and fully connected.
- Disconnect or connect wires to or from this unit only when the power supply is disconnected.
- Use adequate screening in areas of intense Radio Frequency fields.
- Ensure ALL work areas are clear of personnel before operating the controller.
- Follow and abide by local and country health & safety standards.

MVP-R Ramping Controller

The MVP-R controller drives proportional solenoid valves with adjustable ramp times.

Once configured, the settings are permanently stored in the controller memory.

MVP-R Features

- Easily configured using HCT Graphical User Interface (GUI) or HCT Hand Held Interface (HHI)
- LED indication of power, output current and fault status
- Permanently sealed, standard DIN 43650 Form A connector body with pre-wired 18AWG PVC cable
- Single coil applications, programmable enable input
- Output limits are independently adjustable
- Adjustable output with short circuit protection
- Adjustable ramp up and ramp down times (RP1 has ramp up only)

Operating Specifications

Supply Voltage	9 to 28VDC		
Supply Current	Valve current + 20mA (Quiescent Max)		
Output Current	-06A: 600mA MAX	-12A: 1.2A MAX	-25A: 2.5A MAX
Coil Resistance	2Ω MIN.		
Dither Frequency	80, 100, 120, 140, 160, 180, 200, 220, 240, 260, 280, 300. (Select OFF for 1000Hz)		
Ramp Functions	-RP1: ramp up only	-RP2: ramp up and down	
Enable Input Voltage (RP2)	9 to 28VDC		
Operating Temperature Range	-20° to 70° C (operating); -40° to 85° C (storage)		
Enclosure	Glass filled Nylon		
Dimensions	Inch: 2.4 L x 1.2 W x 0.75 H; Mm: 60 L x 30 W x 19 H		

Physical Description



There are two indicator LEDs: STATUS and OUTPUT. The STATUS LED is green when the applied voltage is within the operating range.

The OUTPUT LED is yellow and the brightness will vary with the output current.

In the case of a fault the STATUS LED will flash red with a flash code. See Fault Status for details.

The MVP communicates with the Graphical User Interface through an infrared interface port to RS232. The infrared adapter clips onto the MVPC/D1 aligning with the notches in the sides. It must be powered when configuring the settings.

User Interface

The MVP has a number of internal settings.

Users can open the Graphical User Interface to view, make changes and save the settings in a data file which can be uploaded to any MVP controller.

The Hand Held Interface can also be used to view and make changes, but this device does not have the capability to save the settings in a data file. The programmer, cable and adapter are self-contained which makes the HHI a viable alternative for field work.

Configuration

The GUI has 4 buttons (ran from a PC): Lock, Unlock, Up, and Down. There are short-cut keys: '/'(lock), '*'(unlock), '+'(up), and '-'(down).

The HCT Hand Held Interface has the same 4 buttons and 2-line LCD.



Use the up and down arrows to navigate through the parameter list. The display will show the next parameter in the list when pressed. The parameter name is on the first line and the value is on the second line. The list is in circular, stepping down from the last parameter to the first and vice-versa.

There are three types of parameters: **fixed**; **monitor**; and **variable**. **Fixed** parameters show the module's firmware version, etc. **Monitor** parameters display output current and system voltage. Use **variable** parameters to configure the controller, such as maximum output current, operating mode, etc. Some parameters combine variable and monitor in one line. Use it to set a variable according to the current monitor value.

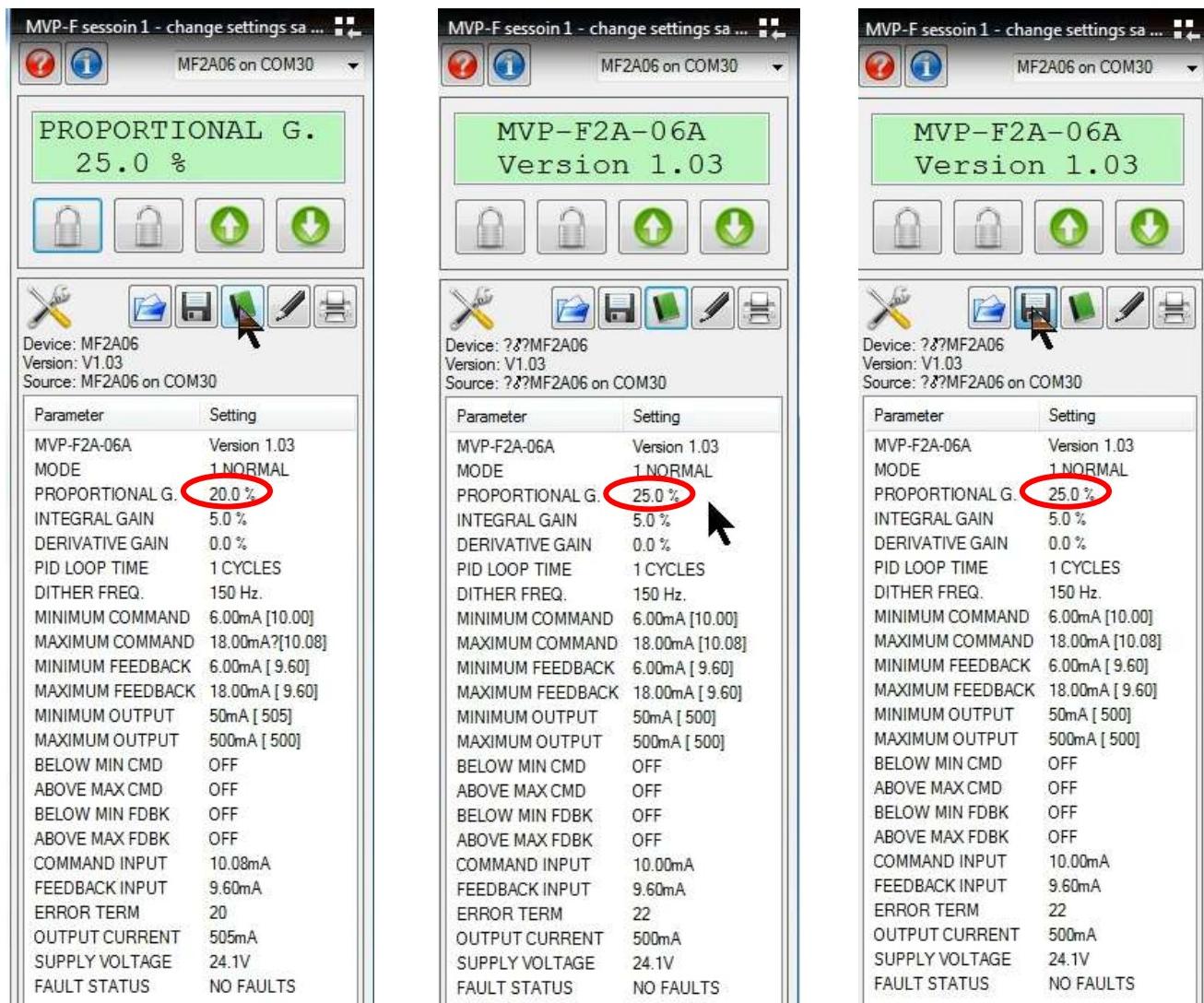
Press the unlock button to enter the edit mode. An asterisk (*) will appear at the beginning of the second line. Use the up and down buttons to change the value. For parameters containing both variable and monitor, the monitor data is in square brackets.

Press the lock button to save the parameters and end edit mode.

When the lock button is pressed, the changes take effect immediately. Change values only when the machine is **NOT** running.

"Read settings from controller" displays a static table of values from non-volatile memory. The changes made to the settings by selecting "lock" are not updated in the table unless "read settings from controller" is selected again.

To save the settings into a file for future use, click "read settings from controller" before clicking "save settings to file".



The screenshots illustrate the sequence of actions to save settings:

- Screenshot 1:** The "PROPORTIONAL G." setting is 25.0 %. The "Save Settings to File" icon (a blue folder with a white document) is highlighted with a cursor.
- Screenshot 2:** The "PROPORTIONAL G." setting has been changed to 20.0 % (circled in red). The "Save Settings to File" icon is now highlighted with a cursor.
- Screenshot 3:** The "PROPORTIONAL G." setting has been changed back to 25.0 % (circled in red). The "Save Settings to File" icon is now highlighted with a cursor.

Device: MF2A06
Version: V1.03
Source: MF2A06 on COM30

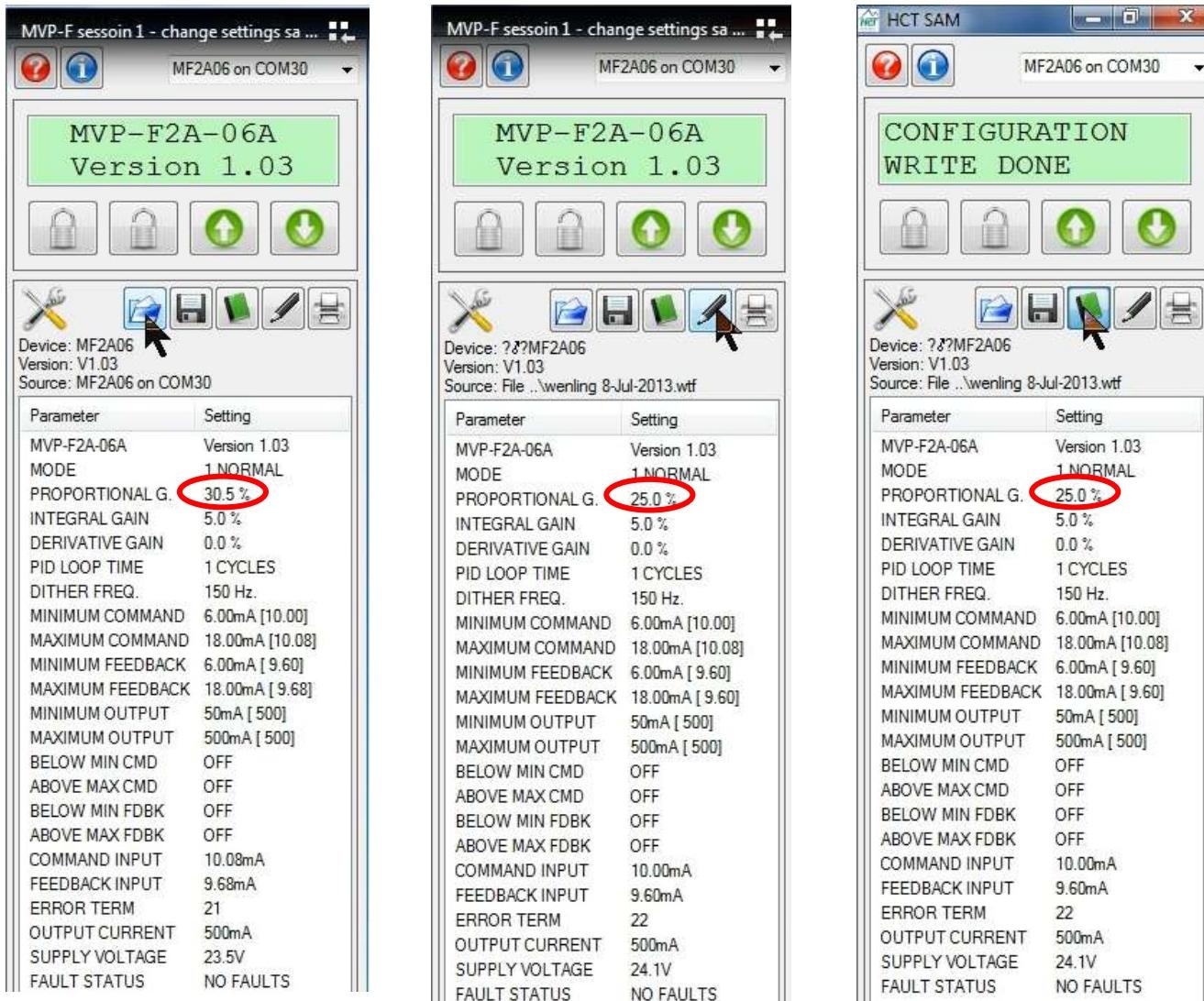
Parameter	Setting
MVP-F2A-06A	Version 1.03
MODE	1 NORMAL
PROPORTIONAL G.	20.0 %
INTEGRAL GAIN	5.0 %
DERIVATIVE GAIN	0.0 %
PID LOOP TIME	1 CYCLES
DITHER FREQ.	150 Hz.
MINIMUM COMMAND	6.00mA [10.00]
MAXIMUM COMMAND	18.00mA [10.08]
MINIMUM FEEDBACK	6.00mA [9.60]
MAXIMUM FEEDBACK	18.00mA [9.60]
MINIMUM OUTPUT	50mA [505]
MAXIMUM OUTPUT	500mA [500]
BELOW MIN CMD	OFF
ABOVE MAX CMD	OFF
BELOW MIN FDBK	OFF
ABOVE MAX FDBK	OFF
COMMAND INPUT	10.08mA
FEEDBACK INPUT	9.60mA
ERROR TERM	20
OUTPUT CURRENT	505mA
SUPPLY VOLTAGE	24.1V
FAULT STATUS	NO FAULTS

Parameter	Setting
MVP-F2A-06A	Version 1.03
MODE	1 NORMAL
PROPORTIONAL G.	25.0 %
INTEGRAL GAIN	5.0 %
DERIVATIVE GAIN	0.0 %
PID LOOP TIME	1 CYCLES
DITHER FREQ.	150 Hz.
MINIMUM COMMAND	6.00mA [10.00]
MAXIMUM COMMAND	18.00mA [10.08]
MINIMUM FEEDBACK	6.00mA [9.60]
MAXIMUM FEEDBACK	18.00mA [9.60]
MINIMUM OUTPUT	50mA [500]
MAXIMUM OUTPUT	500mA [500]
BELOW MIN CMD	OFF
ABOVE MAX CMD	OFF
BELOW MIN FDBK	OFF
ABOVE MAX FDBK	OFF
COMMAND INPUT	10.00mA
FEEDBACK INPUT	9.60mA
ERROR TERM	22
OUTPUT CURRENT	500mA
SUPPLY VOLTAGE	24.1V
FAULT STATUS	NO FAULTS

Parameter	Setting
MVP-F2A-06A	Version 1.03
MODE	1 NORMAL
PROPORTIONAL G.	25.0 %
INTEGRAL GAIN	5.0 %
DERIVATIVE GAIN	0.0 %
PID LOOP TIME	1 CYCLES
DITHER FREQ.	150 Hz.
MINIMUM COMMAND	6.00mA [10.00]
MAXIMUM COMMAND	18.00mA [10.08]
MINIMUM FEEDBACK	6.00mA [9.60]
MAXIMUM FEEDBACK	18.00mA [9.60]
MINIMUM OUTPUT	50mA [500]
MAXIMUM OUTPUT	500mA [500]
BELOW MIN CMD	OFF
ABOVE MAX CMD	OFF
BELOW MIN FDBK	OFF
ABOVE MAX FDBK	OFF
COMMAND INPUT	10.00mA
FEEDBACK INPUT	9.60mA
ERROR TERM	22
OUTPUT CURRENT	500mA
SUPPLY VOLTAGE	24.1V
FAULT STATUS	NO FAULTS

When uploading settings from a data file, the static table shows the settings from the data file, but they are not in the controller yet.

Click “write settings to controller” before clicking “read settings from controller”. After this step, the static table displays the MVP settings from the data file.



The figure consists of three side-by-side screenshots of the HCT SAM software interface, showing the progression of writing settings to a controller.

Screenshot 1: The interface shows the "MVP-F2A-06A Version 1.03" screen. A cursor is hovering over the "File" icon (represented by a document with a blue arrow) in the toolbar. Below the toolbar, the device information is listed: Device: MF2A06, Version: V1.03, Source: MF2A06 on COM30. A table below lists various parameters and their current settings. The "PROPORTIONAL G." row shows a value of 30.5 %, which is circled in red.

Parameter	Setting
MVP-F2A-06A	Version 1.03
MODE	1 NORMAL
PROPORTIONAL G.	30.5 %
INTEGRAL GAIN	5.0 %
DERIVATIVE GAIN	0.0 %
PID LOOP TIME	1 CYCLES
DITHER FREQ.	150 Hz.
MINIMUM COMMAND	6.00mA [10.00]
MAXIMUM COMMAND	18.00mA [10.08]
MINIMUM FEEDBACK	6.00mA [9.60]
MAXIMUM FEEDBACK	18.00mA [9.68]
MINIMUM OUTPUT	50mA [500]
MAXIMUM OUTPUT	500mA [500]
BELOW MIN CMD	OFF
ABOVE MAX CMD	OFF
BELOW MIN FDBK	OFF
ABOVE MAX FDBK	OFF
COMMAND INPUT	10.08mA
FEEDBACK INPUT	9.68mA
ERROR TERM	21
OUTPUT CURRENT	500mA
SUPPLY VOLTAGE	23.5V
FAULT STATUS	NO FAULTS

Screenshot 2: The interface shows the same screen after writing the settings. The "File" icon is now highlighted with a cursor. The "PROPORTIONAL G." value has been updated to 25.0 %, also circled in red.

Parameter	Setting
MVP-F2A-06A	Version 1.03
MODE	1 NORMAL
PROPORTIONAL G.	25.0 %
INTEGRAL GAIN	5.0 %
DERIVATIVE GAIN	0.0 %
PID LOOP TIME	1 CYCLES
DITHER FREQ.	150 Hz.
MINIMUM COMMAND	6.00mA [10.00]
MAXIMUM COMMAND	18.00mA [10.08]
MINIMUM FEEDBACK	6.00mA [9.60]
MAXIMUM FEEDBACK	18.00mA [9.68]
MINIMUM OUTPUT	50mA [500]
MAXIMUM OUTPUT	500mA [500]
BELOW MIN CMD	OFF
ABOVE MAX CMD	OFF
BELOW MIN FDBK	OFF
ABOVE MAX FDBK	OFF
COMMAND INPUT	10.00mA
FEEDBACK INPUT	9.60mA
ERROR TERM	22
OUTPUT CURRENT	500mA
SUPPLY VOLTAGE	24.1V
FAULT STATUS	NO FAULTS

Screenshot 3: The interface shows the "CONFIGURATION WRITE DONE" screen. The "File" icon is highlighted with a cursor. The "PROPORTIONAL G." value has been updated to 25.0 %, also circled in red.

Parameter	Setting
MVP-F2A-06A	Version 1.03
MODE	1 NORMAL
PROPORTIONAL G.	25.0 %
INTEGRAL GAIN	5.0 %
DERIVATIVE GAIN	0.0 %
PID LOOP TIME	1 CYCLES
DITHER FREQ.	150 Hz.
MINIMUM COMMAND	6.00mA [10.00]
MAXIMUM COMMAND	18.00mA [10.08]
MINIMUM FEEDBACK	6.00mA [9.60]
MAXIMUM FEEDBACK	18.00mA [9.68]
MINIMUM OUTPUT	50mA [500]
MAXIMUM OUTPUT	500mA [500]
BELOW MIN CMD	OFF
ABOVE MAX CMD	OFF
BELOW MIN FDBK	OFF
ABOVE MAX FDBK	OFF
COMMAND INPUT	10.00mA
FEEDBACK INPUT	9.60mA
ERROR TERM	22
OUTPUT CURRENT	500mA
SUPPLY VOLTAGE	24.1V
FAULT STATUS	NO FAULTS

Parameter List

The following table outlines the MVP-R parameters as well as the limits and units of measure for each parameter.

Parameter	Limits	Units
MVP-RPx-xxx		Version #
Ramp time factor	X1, /10	Mode #
Ramp up time	0.0 to 120.0	Seconds
Ramp down time*	0.0 to 120.0	Seconds
Minimum output	0 to 600**	mA
Maximum output	0 to 600**	mA
Dither frequency	80 to 300, (select OFF for 1000Hz)	Hz.
Output current		mA
Supply voltage		Volts
Fault status		Fault

*RP2 only

0 to 1.2A for **-12A version, 0 to 2.5A for **-25A** version

MVP-RPx-xxx - The title parameter is fixed. It displays the model number and the firmware version.

RAMP TIME FACTOR – Sets the rate of change for the output current. If the Ramp Time Factor is x1, the ramp time will match the ramp time settings. If it is set to 1/10, the ramp time will be 1/10 of the ramp time setting.

RAMP UP/DOWN TIME - Sets the rate of change for Output current.

For RP1, the output current increases from Minimum to Maximum.

For RP2, the output current is initially set to the Minimum.

- The output current increases from Minimum to Maximum within the Ramp Up time when switching ON “ENABLE” switch.
- The output current decreases from Maximum to Minimum within the Ramp Down time when switching OFF “ENABLE” switch.

MIN OUTPUT - Sets the minimum output current (milliamps, amps for -12A,-25A). The value in the brackets is the present output current.

MAX OUTPUT - Sets the maximum output current (milliamps, amps for -12A,-25A). The value in the brackets is the present output current.

DITHER FREQ. – Options: 80, 100, 120, 140, 160, 180, 200, 220, 240, 260, 280, 300, (Select OFF for 1000Hz).

Set the PWM or dither frequency according to the valve specifications. This parameter is variable.

OUTPUT CURRENT - Displays the present output current. This parameter is a monitor type.

SUPPLY VOLTAGE - Displays the module’s power supply voltage. It is helpful for troubleshooting. This parameter is a monitor type.

FAULT STATUS - The STATUS LED will flash red 2 times for Coil Open and 3 times for Coil Short.

Wiring

MVP-RP1:

Terminal	Function
Brown	+PWR
Blue	PWR GND
GRN/YEL	Connector GND

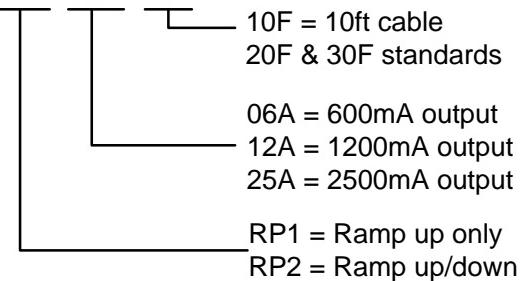
MVP-RP2

Terminal	Function
Brown	+PWR
Blue	PWR GND
Black	Enable Input
White	not used
Red	not used
GRN/YEL	Connector GND

Order Information

The following is a break-down of the MVPR part numbering system:

MVP-RP1-06A-10F



Required Communication Cables:

For the Hand Held Interface Device: P/N: CBL-IRA

For the PC software SAM: PN: CBL-IRMU



P/N: CBL-IRA



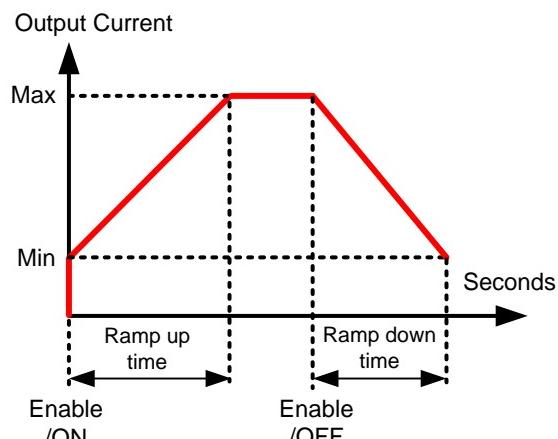
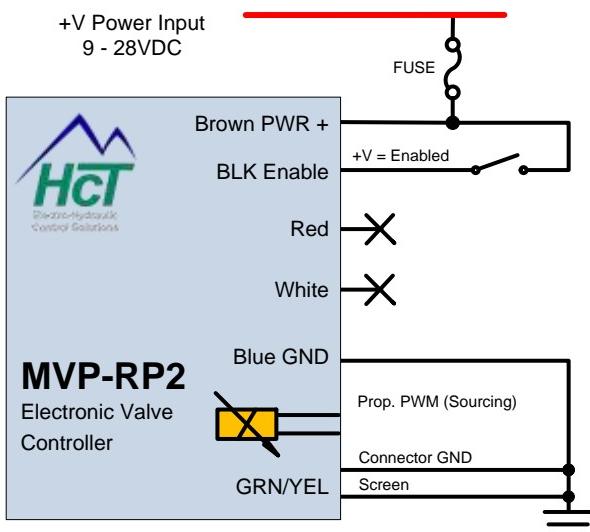
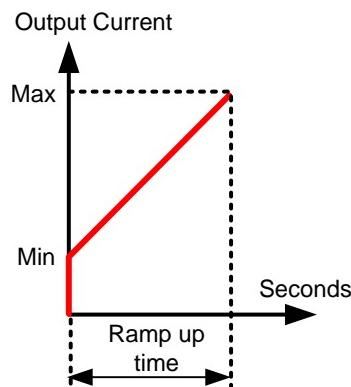
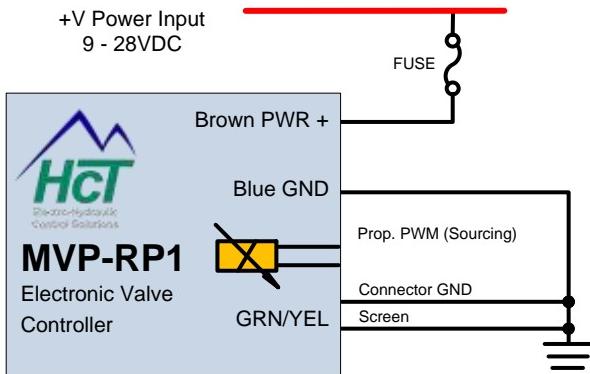
P/N: CBL-IRMU

Application Examples

Single Solenoid Control

The MVP can drive a single solenoid.

Set the dither and output settings according to the valve specifications.



- ❖ Mining & Exploration
- ❖ Agriculture
- ❖ Cranes & lifts
- ❖ Refuse & Re-cycling
- ❖ Construction
- ❖ Off-Road vehicles
- ❖ Forestry, Wood & Pulp
- ❖ Reclamation & Salvage
- ❖ Oil Field & Sands
- ❖ Demolition Equipment
- ❖ Cooling Solutions
- ❖ Military Apparatus
- ❖ Specialty Use
- ❖ Remote Control
- ❖ Power Generation
- ❖ Emission Controls
- ❖ Integrated Drivers
- ❖ Valve & Pump Controls



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